



# Zephyr<sup>®</sup> Project

## Developer Summit

# Introducing the Zephyr Input Subsystem

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fabiofw

# Why?



**o7-machinehum** commented on Jan 11 • edited ▾

Author ...

RE for the input subsystem, it seems like that isn't happening [#48342](#)

Does an input subsystem make sense for an embedded RTOS?

# Existing APIs

# zephyr/include/zephyr/drivers/kscan.h

```
48  /**
49   * @cond INTERNAL_HIDDEN
50   *
51   * Keyboard scan driver API definition and system call entry points.
52   *
53   * (Internal use only.)
54   */
55  typedef int (*kscan_config_t)(const struct device *dev,
56                               kscan_callback_t callback);
57  typedef int (*kscan_disable_callback_t)(const struct device *dev);
58  typedef int (*kscan_enable_callback_t)(const struct device *dev);
59
60  __subsystem struct kscan_driver_api {
61      kscan_config_t config;
62      kscan_disable_callback_t disable_callback;
63      kscan_enable_callback_t enable_callback;
64  };
```

# Single listener

```
28 struct xpt2046_data {  
29     const struct device *dev;  
30     kscan_callback_t callback;  
31     struct gpio_callback int_gpio_cb;  
32     bool enabled;
```

```
183 static int xpt2046_configure(const struct device *dev, kscan_callback_t callback)  
184 {  
185     struct xpt2046_data *data = dev->data;  
186  
187     if (!callback) {  
188         LOG_ERR("Callback is null");  
189         return -EINVAL;  
190     }  
191     LOG_DBG("%s: set callback", dev->name);  
192  
193     data->callback = callback;  
194  
195     return 0;  
196 }
```

# Limited use cases

```
35  /**
36   * @brief Keyboard scan callback called when user press/release
37   * a key on a matrix keyboard.
38   *
39   * @param dev Pointer to the device structure for the driver instance.
40   * @param row Describes row change.
41   * @param column Describes column change.
42   * @param pressed Describes the kind of key event.
43   */
44  typedef void (*kscan_callback_t)(const struct device *dev, uint32_t row,
45                                  uint32_t column,
46                                  bool pressed);
```



# Redundant APIs

```
1036 int bmi160_pm(const struct device *dev, enum pm_device_action action)
1037 {
1038     int ret = 0;
1039
1040     switch (action) {
1041     case PM_DEVICE_ACTION_RESUME:
1042         bmi160_resume(dev);
1043         break;
1044     case PM_DEVICE_ACTION_SUSPEND:
1045         bmi160_suspend(dev);
1046         break;
1047     default:
1048         ret = -ENOTSUP;
1049     }
1050
1051     return ret;
1052 }
```



# Capsense

```
1  # Copyright (c) 2022 Keiya Nobuta
2  # SPDX-License-Identifier: Apache-2.0
3
4  description: CAP1203 3-channel capacitive touch sensor
5
6  compatible: "microchip,cap1203"
7
8  include: [kscan.yaml, i2c-device.yaml]
9
10 properties:
11   int-gpios:
12     type: phandle-array
```

```
90  /*
91   * Clear INT bit to clear SENSOR INPUT STATUS bits.
92   * Note that this is also required in polling mode.
93   */
94  r = cap1203_clear_interrupt(&config->i2c);
95  if (r < 0) {
96      return r;
97  }
98
99  data->callback(dev, 0, col, pressed);
```

# Row, column... it's a touchscreen!

```
1  # Copyright (c) 2020 NXP
2  # SPDX-License-Identifier: Apache-2.0
3
4  description: FT5XX6/FT6XX6 capacitive touch panels
5
6  compatible: "focaltech,ft5336"
7
8  include: [kscan.yaml, i2c-device.yaml]
9
10 properties:
11   int-gpios:
12     type: phandle-array
13
14   event = (coords[0] >> EVENT_POS) & EVENT_MSK;
15   row = ((coords[0] & POSITION_H_MSK) << 8U) | coords[1];
16   col = ((coords[2] & POSITION_H_MSK) << 8U) | coords[3];
17   pressed = (event == EVENT_PRESS_DOWN) || (event == EVENT_CONTACT);
18
19   LOG_DBG("event: %d, row: %d, col: %d", event, row, col);
20
21   data->callback(dev, row, col, pressed);
```

# Don't even try

```
25  /**
26   * @brief GPIO Keys Driver APIs
27   * @defgroup gpio_keys_interface GPIO KeysDriver APIs
28   * @ingroup io_interfaces
29   * @{
30   */
31
32  __subsystem struct gpio_keys_api {
33      int (*enable_interrupt)(const struct device *dev, gpio_keys_callback_handler_t cb);
34      int (*disable_interrupt)(const struct device *dev);
35      int (*get_pin)(const struct device *dev, uint32_t idx);
36  };
```

# It's not an input device, it's a sensor

```
4  description: Nordic nRF quadrature decoder (QDEC) node
5
6  compatible: "nordic,nrf-qdec"
7
8  include: [sensor-device.yaml, pinctrl-device.yaml]
```

```
100
101 BUILD_ASSERT(QDEC_STEPS > 0, "only positive number valid");
102 BUILD_ASSERT(QDEC_STEPS <= 2048, "overflow possible");
103
```

```
104 val->val1 = (acc * FULL_ANGLE) / steps;
105 val->val2 = (acc * FULL_ANGLE) - (val->val1 * steps);
106 if (val->val2 != 0) {
107     val->val2 *= 1000000;
108     val->val2 /= steps;
109 }
110
```

```
111 return 0;
```

```
127 /** Resistance , in Ohm */
128 SENSOR_CHAN_RESISTANCE,
```

```
129
130 /** Angular rotation, in degrees */
131 SENSOR_CHAN_ROTATION,
```

```
132
133 /** Position change on the X axis, in points. */
134 SENSOR_CHAN_POS_DX,
```

```
102 BUILD_ASSERT(CONFIG_DESKTOP_WHEEL_SENSOR_VALUE_DIVIDER > 0,
103               "Divider must be non-negative");
```

```
104 if (CONFIG_DESKTOP_WHEEL_SENSOR_VALUE_DIVIDER > 1) {
105     wheel /= CONFIG_DESKTOP_WHEEL_SENSOR_VALUE_DIVIDER;
106 }
107
```

```
108 event->wheel = MAX(MIN(wheel, SCHAR_MAX), SCHAR_MIN);
```

<https://github.com/zephyrproject-rtos/zephyr/blob/60a20471b561a0a3a74b377991fe1976c2ea83d7/dts/bindings/sensor/nordic%2Cnrf-qdec.yaml>

<https://github.com/zephyrproject-rtos/zephyr/blob/60a20471b561a0a3a74b377991fe1976c2ea83d7/include/zephyr/drivers/sensor.h#L131>

[https://github.com/zephyrproject-rtos/zephyr/blob/60a20471b561a0a3a74b377991fe1976c2ea83d7/drivers/sensor/qdec\\_nrfx/qdec\\_nrfx.c#L104-L109](https://github.com/zephyrproject-rtos/zephyr/blob/60a20471b561a0a3a74b377991fe1976c2ea83d7/drivers/sensor/qdec_nrfx/qdec_nrfx.c#L104-L109)

[https://github.com/nrfconnect/sdk-nrf/blob/f3d31cc926d75ef5933259c2e998d34794a225bc/applications/nrf\\_desktop/src/hw\\_interface/wheel.c#L104-L106](https://github.com/nrfconnect/sdk-nrf/blob/f3d31cc926d75ef5933259c2e998d34794a225bc/applications/nrf_desktop/src/hw_interface/wheel.c#L104-L106)

# Previous attempts



# Device specific: touchscreen API

```
32 + typedef bool (*single_tap_get_t)(const struct device *dev);
33 + typedef bool (*two_finger_tap_get_t)(const struct device *dev);
34 + typedef int16_t (*x_pos_get_abs_t)(const struct device *dev);
35 + typedef int16_t (*y_pos_get_abs_t)(const struct device *dev);
36 + typedef int16_t (*x_pos_get_rel_t)(const struct device *dev);
37 + typedef int16_t (*y_pos_get_rel_t)(const struct device *dev);
38 + typedef int (*num_fingers_get_t)(const struct device *dev);
39 +
40 + __subsystem struct touch_driver_api {
41 +     single_tap_get_t single_tap;
42 +     two_finger_tap_get_t two_finger_tap;
43 +     x_pos_get_abs_t x_pos_abs;
44 +     y_pos_get_abs_t y_pos_abs;
45 +     x_pos_get_rel_t x_pos_rel;
46 +     y_pos_get_rel_t y_pos_rel;
47 +     num_fingers_get_t num_fingers;
48 + };
```

# Application Specific

```
143 + enum keyboard_value {  
144 +     KEY_RELEASE,  
145 +     KEY_PRESSED,  
146 +     KEY_LONG_PRESSED,
```



**petejohanson** on Dec 28, 2022

Contributor ...

Why are these added. As soon as you have long press/release, why not support double tap? Triple?

If the goal is a "lowest common denominator" API good enough for basic input to programs, this is probably fine.

I think maybe this is my disconnect, I come from developing featureful input devices.

If the goal of this API is to focus on the *consumers* of input data, then we should clearly document that, since the current system doesn't seem to be flexible/powerful enough to handle the other.

```
147 +     KEY_HOLD_PRESSED,  
148 +     KEY_LONG_RELEASE  
149 + };
```





**gmarull** requested changes on Nov 23, 2022

[View reviewed changes](#)

**gmarull** left a comment

Member ...

I think we really need an input subsystem, not another API to handle a type of input device (touch).



**o7-machinehum** commented on Nov 30, 2022

Author ...

Please don't keep opening PRs and update [#51493](#). My comments still apply.

Okay, so what's my action here? Do you want me to develop an entire input system?

# Linux Input Events

# Allocate your device

<u>292</u>
<u>293</u>
<u>294</u>
<u>295</u>
<u>296</u>

```
idev = devm_input_allocate_device(&spi->dev);  
if (!idev) {  
    dev_err(&spi->dev, "failed to allocate input device\n");  
    return -ENOMEM;  
}
```

# Set capabilities

<u>315</u>	<u><a href="#">input_set_abs_params(idev, ABS_RX, 0, 255, 0, 0);</a></u>
<u>316</u>	<u><a href="#">input_set_abs_params(idev, ABS_RY, 0, 255, 0, 0);</a></u>
<u>317</u>	<u><a href="#">input_set_capability(idev, EV_KEY, BTN_DPAD_UP);</a></u>
<u>318</u>	<u><a href="#">input_set_capability(idev, EV_KEY, BTN_DPAD_DOWN);</a></u>
<u>319</u>	<u><a href="#">input_set_capability(idev, EV_KEY, BTN_DPAD_LEFT);</a></u>
<u>320</u>	<u><a href="#">input_set_capability(idev, EV_KEY, BTN_DPAD_RIGHT);</a></u>
<u>321</u>	<u><a href="#">input_set_capability(idev, EV_KEY, BTN_A);</a></u>
<u>322</u>	<u><a href="#">input_set_capability(idev, EV_KEY, BTN_B);</a></u>

# Register a device

361  
362  
363  
364  
365  
366  
367  
368

```
/* register input poll device */  
err = input_register_device(idev);  
if (err) {  
    dev_err(&spi->dev,  
            "failed to register input device: %d\n", err);  
    return err;  
}
```

# Send reports and sync

```
223 switch (pad->response[1]) {
224 case 0xCE:
...
229     input_report_abs(input, ABS_X, REVERSE_BIT(pad->response[7]));
230     input_report_abs(input, ABS_Y, REVERSE_BIT(pad->response[8]));
231     input_report_abs(input, ABS_RX, REVERSE_BIT(pad->response[5]));
232     input_report_abs(input, ABS_RY, REVERSE_BIT(pad->response[6]));
233     input_report_key(input, BTN_DPAD_UP, b_rsp3 & BIT(3));
234     input_report_key(input, BTN_DPAD_DOWN, b_rsp3 & BIT(1));
235     input_report_key(input, BTN_DPAD_LEFT, b_rsp3 & BIT(0));
236     input_report_key(input, BTN_DPAD_RIGHT, b_rsp3 & BIT(2));
...
277 }
278
279 input_sync(input);
```



# Receive events from /dev/input/event<n>

```
28 struct input_event {  
...  
30     struct timeval time;  
...  
44     u16 type;  
45     u16 code;  
46     s32 value;  
47 };
```

```
$ evtest /dev/input/event3  
**  
Event: time 1685527363.847893, type 2 (EV_REL), code 1 (REL_Y), value -1  
Event: time 1685527363.847893, ----- SYN_REPORT -----  
Event: time 1685527363.852845, type 2 (EV_REL), code 1 (REL_Y), value -1  
Event: time 1685527363.852845, ----- SYN_REPORT -----  
Event: time 1685527363.855885, type 2 (EV_REL), code 0 (REL_X), value 1  
Event: time 1685527363.855885, type 2 (EV_REL), code 1 (REL_Y), value -1  
Event: time 1685527363.855885, ----- SYN_REPORT -----  
Event: time 1685527364.122898, type 4 (EV_MSC), code 4 (MSC_SCAN), value 90001  
Event: time 1685527364.122898, type 1 (EV_KEY), code 272 (BTN_LEFT), value 1  
Event: time 1685527364.122898, ----- SYN_REPORT -----  
Event: time 1685527364.225859, type 4 (EV_MSC), code 4 (MSC_SCAN), value 90001  
Event: time 1685527364.225859, type 1 (EV_KEY), code 272 (BTN_LEFT), value 0  
Event: time 1685527364.225859, ----- SYN_REPORT -----
```



# Zephyr Implementation

# Zephyr Input Subsystem proposal [#54622](#)

## TL:DR;

Linux-like events for Zephyr, proof of concept here: [#54620](#)

## Requirements:

- Support a many-to-many model, register listeners at build time
- Support events from any type of input device without special functions
- Backwards compatible with kscan
- Provide a framework for extensibility

# Input Event structure

```
34  struct input_event {
35      /** Device generating the event or NULL. */
36      const struct device *dev;
37      /** Sync flag. */
38      uint8_t sync;
39      /** Event type (see @ref INPUT_EV_CODES). */
40      uint8_t type;
41      /**
42       * Event code (see @ref INPUT_KEY_CODES, @ref INPUT_BTN_CODES,
43       * @ref INPUT_ABS_CODES, @ref INPUT_REL_CODES, @ref INPUT_MSC_CODES).
44       */
45      uint16_t code;
46      /** Event value. */
47      int32_t value;
48  };
```

# Driver API: gpio-keys

```
/**
 * @brief Report a new @ref INPUT_EV_KEY input event, note that value is
 * converted to either 0 or 1.
 *
 * @see input_report() for more details.
 */
static inline int input_report_key(const struct device *dev,
                                   uint16_t code, int32_t value, bool sync,
                                   k_timeout_t timeout)
{
    return input_report(dev, INPUT_EV_KEY, code, !!value, sync, timeout);
}

64         /* If gpio changed, report the event */
65         if (new_pressed != pin_data->cb_data.pin_state) {
66             pin_data->cb_data.pin_state = new_pressed;
67             LOG_DBG("Report event %s %d, code=%d", dev->name, new_pressed,
68                   pin_cfg->zephyr_code);
69             input_report_key(dev, pin_cfg->zephyr_code, new_pressed, true, K_FOREVER);
70         }
```

# Driver API: touchscreen

```
101     LOG_DBG("event: %d, row: %d, col: %d", event, row, col);
102
103     if (pressed) {
104         input_report_abs(dev, INPUT_ABS_X, col, false, K_FOREVER);
105         input_report_abs(dev, INPUT_ABS_Y, row, false, K_FOREVER);
106         input_report_key(dev, INPUT_BTN_TOUCH, 1, true, K_FOREVER);
107     } else if (data->pressed_old && !pressed) {
108         input_report_key(dev, INPUT_BTN_TOUCH, 0, true, K_FOREVER);
109     }
110     data->pressed_old = pressed;
```

# Application API

```
8  #include <zephyr/input/input.h>
9
10 static void input_cb(struct input_event *evt)
11 {
12     printf("input event: dev=%-16s %3s type=%2x code=%3d value=%d\n",
13           evt->dev ? evt->dev->name : "NULL",
14           evt->sync ? "SYN" : "",
15           evt->type,
16           evt->code,
17           evt->value);
18 }
19 INPUT_LISTENER_CB_DEFINE(NULL, input_cb);
```



# Modes of operation

```
21 choice INPUT_MODE
22     prompt "Input event processing mode"
23     default INPUT_MODE_THREAD
24
25 config INPUT_MODE_SYNCHRONOUS
26     bool "Process input events synchronously"
27     help
28         Input events callbacks are processed synchronously in the context of
29         the code that is reporting the event.
30
31 config INPUT_MODE_THREAD
32     bool "Process input events in a dedicated thread"
33     depends on MULTITHREADING
34     help
35         Input events are added to a message queue and the callbacks are
36         processed asynchronously in a dedicated thread.
37
38 endchoice
```



# Kscan compatibility

```
3
4  description: |
5      Input to kscan adapter.
6
7      Allows using an input device with the kscan API. Define as a child node of
8      the input device, for example
9
10     chosen {
11         zephyr,keyboard-scan = &kscan_input;
12     };
13
14     ft5336@38 {
15         ...
16         kscan_input: kscan-input {
17             compatible = "zephyr,kscan-input";
18         };
19     };
20
21     compatible: "zephyr,kscan-input"
22
23     include: kscan.yaml
```

# Kscan compatibility

```
26 static void kscan_input_cb(const struct device *dev, struct input_event *evt)
27 {
28     struct kscan_input_data *data = dev->data;
29
30     switch (evt->code) {
31     case INPUT_ABS_X:
32         data->col = evt->value;
33         break;
34     case INPUT_ABS_Y:
35         data->row = evt->value;
36         break;
37     case INPUT_BTN_TOUCH:
38         data->pressed = evt->value;
39         break;
40     }
41
42     if (evt->sync) {
43         LOG_DBG("input event: %3d %3d %d",
44             data->row, data->col, data->pressed);
45         if (data->callback) {
46             data->callback(dev, data->row, data->col, data->pressed);
47         }
48     }
49 }
```

# Extensibility

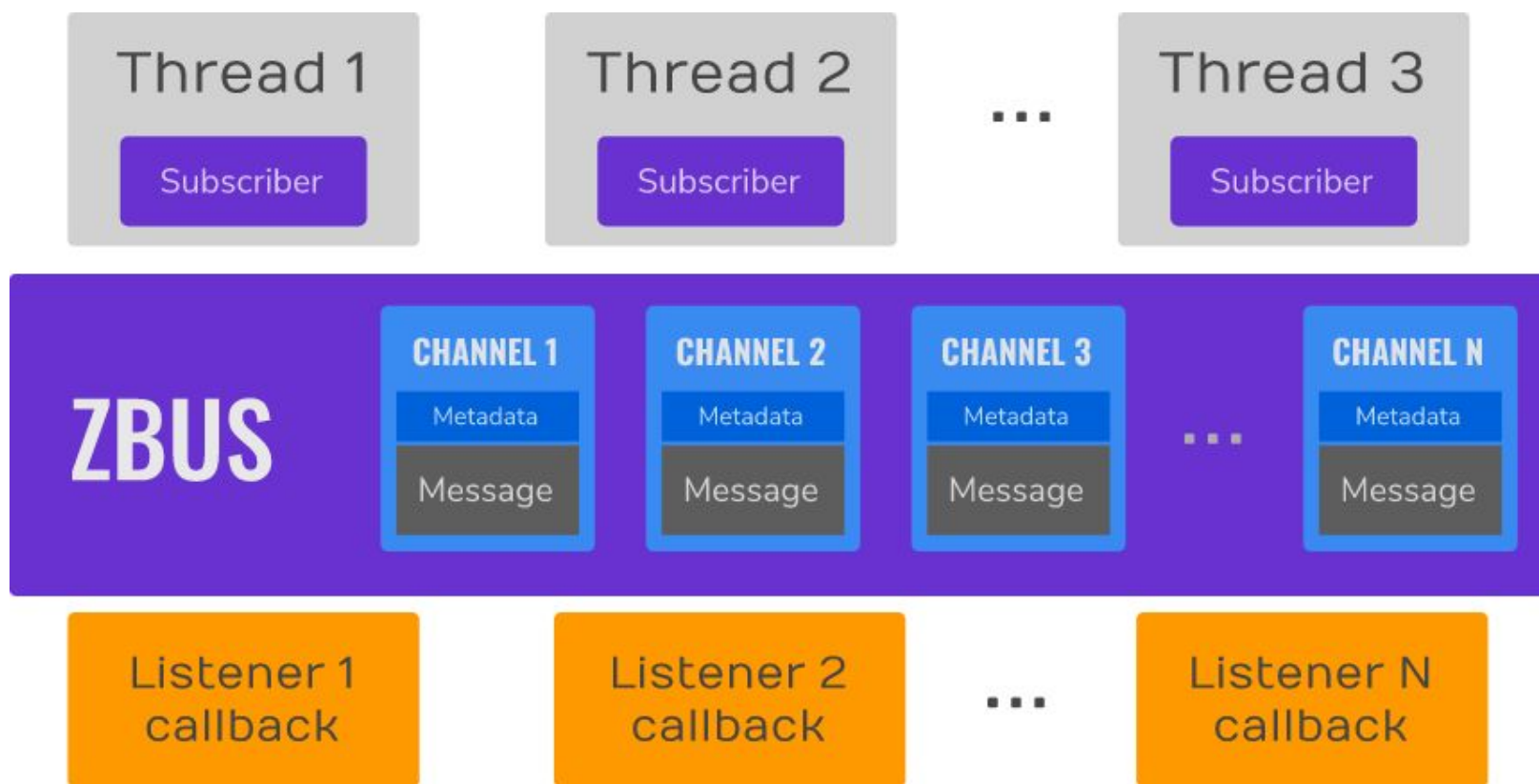
```
20  /**
21   * @name Input event types.
22   * @anchor INPUT_EV_CODES
23   * @{
24   */
25  #define INPUT_EV_KEY 0x01
26  #define INPUT_EV_REL 0x02
27  #define INPUT_EV_ABS 0x03
28  #define INPUT_EV_MSC 0x04
29  #define INPUT_EV_VENDOR_START 0xf0
30  #define INPUT_EV_VENDOR_STOP 0xff
31  /** @} */
```

# Filters and event reprocessing

```
4  description: |
5      Input longpress pseudo-device
6
7      Listens for key events as an input and produces key events as output
8      corresponding to short and long press.
9
10     Can be optionally be associated to a specific device to listen for events
11     only from that device. Example configuration:
12
13     #include <dt-bindings/input/input-event-codes.h>
14
15     longpress {
16         input = <&buttons>;
17         compatible = "zephyr,input-longpress";
18         input-codes = <INPUT_KEY_0>, <INPUT_KEY_1>;
19         short-codes = <INPUT_KEY_A>, <INPUT_KEY_B>;
20         long-codes = <INPUT_KEY_X>, <INPUT_KEY_Y>;
21         long-delay-ms = <1000>;
22     };
```

# Event Systems

# Zbus





# ZMK event system

```
45  #define ZMK_EVENT_IMPL(event_type) \
46      const struct zmk_event_type zmk_event_##event_type = {.name = STRINGIFY(event_type)}; \
47      const struct zmk_event_type *zmk_event_ref_##event_type __used \
48          __attribute__((__section__(".event_type"))) = &zmk_event_##event_type; \
49      struct event_type##_event *new_##event_type(struct event_type data) { \
50          struct event_type##_event *ev = \
51              (struct event_type##_event *)k_malloc(sizeof(struct event_type##_event)); \
52          ev->header.event = &zmk_event_##event_type; \
53          ev->data = data; \
54          return ev; \
55      }; \
56      struct event_type *as_##event_type(const zmk_event_t *eh) { \
57          return (eh->event == &zmk_event_##event_type) ? &((struct event_type##_event *)eh)->data \
58              : NULL; \
59      };
```



# ZMK event processing

```
32 K_MSGQ_DEFINE(zmk_kscan_msgq, sizeof(struct zmk_kscan_event), CONFIG_ZMK_KSCAN_EVENT_QUEUE_SIZE, 4);
33
34 static void zmk_kscan_callback(const struct device *dev, uint32_t row, uint32_t column,
35                               bool pressed) {
36     struct zmk_kscan_event ev = {
37         .row = row,
38         .column = column,
39         .state = (pressed ? ZMK_KSCAN_EVENT_STATE_PRESSED : ZMK_KSCAN_EVENT_STATE_RELEASED)};
40
41     k_msgq_put(&zmk_kscan_msgq, &ev, K_NO_WAIT);
42     k_work_submit(&msg_processor.work);
43 }
44
45 void zmk_kscan_process_msgq(struct k_work *item) {
46     struct zmk_kscan_event ev;
47
48     while (k_msgq_get(&zmk_kscan_msgq, &ev, K_NO_WAIT) == 0) {
49         bool pressed = (ev.state == ZMK_KSCAN_EVENT_STATE_PRESSED);
50         uint32_t position = zmk_matrix_transform_row_column_to_position(ev.row, ev.column);
51         LOG_DBG("Row: %d, col: %d, position: %d, pressed: %s", ev.row, ev.column, position,
52               (pressed ? "true" : "false"));
53         ZMK_EVENT_RAISE(new_zmk_position_state_changed(
54             (struct zmk_position_state_changed){.source = ZMK_POSITION_STATE_CHANGE_SOURCE_LOCAL,
55                                                  .state = pressed,
56                                                  .position = position,
57                                                  .timestamp = k_uptime_get()}));
58     }
59 }
```


# NCS event manager

```
117 void * __weak app_event_manager_alloc(size_t size)
118 {
119     void *event = k_malloc(size);
120
121     if (unlikely(!event)) {
122         LOG_ERR("Application Event Manager OOM error\n");
123         __ASSERT_NO_MSG(false);
124         if (IS_ENABLED(CONFIG_REBOOT)) {
125             sys_reboot(SYS_REBOOT_WARM);
126         } else {
127             k_panic();
128         }
129         return NULL;
130     }
131
132     return event;
133 }
```

# What now?

# State of the Input subsystem


main ▾ **zephyr** / drivers / input /

 **fabiobaltieri** and **carlescufi** input: npcx

..

- CMaLists.txt
- Kconfig
- Kconfig.ft5336
- Kconfig.gpio\_keys
- Kconfig.npcx
- Kconfig.sdl
- input\_ft5336.c
- input\_gpio\_keys.c
- input\_npcx\_kbd.c
- input\_sdl\_touch.c

main ▾ **zephyr** / subsys / input /

 **gmarull** and **carlescufi** iterable\_sections: move

..

- CMaLists.txt
- Kconfig
- input.c
- input\_longpress.c

# Next

- Finish converting the existing drivers
- Zbus integration
- Add some common code for keyboard scanning matrixes
- Write native sinks for LVGL
- Deprecate Kscan

# Send patches!

## Contribution Guidelines

As an open-source project, we welcome and encourage the community to submit patches directly to the project. In our collaborative open source environment, standards and methods for submitting changes help reduce the chaos that can result from an active development community.

This document explains how to participate in project conversations, log bugs and enhancement requests, and submit patches to the project so your patch will be accepted quickly in the codebase.



# Questions